# Normal Forms of Vector Fields 

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## 1 Introduction and notations

As a well-known fact, a vector field $X \in \Gamma(T M)$ non-vanishing at a point $x_{0}$ can be represented as $\frac{\partial}{\partial s_{1}}$ for some coordinate chart $\left(U, \phi=\left(s_{1}, s_{2}, \ldots, s_{n}\right)\right)$ near that point, which means that $X$ can be sent on a locally constant vector field through some diffeomorphism. However, there is not such a good local representation around singular points. The aim of this presentation is to show a relatively good local result formulated in [2], and to show its concrete applications.

Since the problem is local, we may well consider vector fields defined on a neighbourhood of $x_{0}=0 \in \mathbb{R}^{n}$ and vanishing at 0 . We denote this set by $\mathcal{X}$. Note that $\mathcal{X}$ is preserved by the Lie bracket, so $(\mathcal{X},[])$ is a Lie algebra. We also define $\mathcal{G}$ as the group of local diffeomorphisms of $\mathbb{R}^{n}$ that fix 0 . We shall later study the action of $\mathcal{G}$ on $\mathcal{X}$.

We will frequently use the natural identification $T \mathbb{R}^{n} \approx \mathbb{R}^{n+n}$ without mentioning it. Under this identification, we can also see $X \in \mathcal{X}$ as a function $X: U \ni 0 \rightarrow \mathbb{R}^{n}$. For any function $\phi: U \ni 0 \rightarrow \mathbb{R}^{n}$, we denote $[\phi]^{k}$ the up to $k$-th Taylor development of $\phi$ at 0 and $[\phi]_{l}$ the $l$-th homogenous term of its Taylor development at 0 . If $\mathcal{Y}$ is a subalgebra of $\mathcal{X}$, we denote $\mathcal{Y}^{k}:=\left\{[Y]^{k}, Y \in \mathcal{Y}\right\}$ and $\mathcal{Y}_{k}:=\left\{[Y]_{k}, Y \in \mathcal{Y}\right\}$. In the following text, we always consider subalgebras $\mathcal{Y}$ that satisfy an additional condition:

$$
\forall k \in \mathbb{N}, \mathcal{Y}_{k} \subseteq \mathcal{Y}
$$

and we call them graded subalgebras as a reminder.
Finally, for $X \in \mathcal{X}$, as $A=[X]^{1}=[X]_{1}$ is the linear part of $X$ at 0 , we see it as a matrix of $\mathcal{M}(n, \mathbb{R})$.

## 2 Statement of the main Theorem

Recall the Jordan-Dunford decomposition of matrix: for any $A \in \mathcal{M}(n, \mathbb{R})$, $\exists!A_{s} \in \mathcal{M}(n, \mathbb{R}), A_{n} \in \mathcal{M}(n, \mathbb{R})$ such that $A=A_{s}+A_{n}$ where $A_{s}$ is diagonalisable, $A_{n}$ is nilpotent, and $\left[A_{s}, A_{n}\right]=0$.

Theorem 1. Let $\mathcal{Y}$ be a graded subalgebra of $\mathcal{X}, X \in \mathcal{Y}$ a vector field with $A=[X]_{1}$. We consider a matrix $B$ which satisfies one of the two conditions:

- $B=A_{s}$.
- $B \in \mathcal{Y}_{1}$ and $B$ is adjoint to $A$ under some inner product over $\mathbb{R}^{n}$.

Then there exists a sequence $Y_{i} \in \mathcal{Y}_{i}, i \geqslant 2$, such that for any $k \geqslant 2$, $\left[\left(\varphi_{Y_{2}+\ldots+Y_{k}}^{1}\right)_{*} X-A\right]^{k}$ commutes with $B$, where $\varphi_{Y_{2}+\ldots+Y_{k}}^{t}$ is the flow of $Y_{2}+\ldots+Y_{k}$ at time $t$.

Remark 1. We shall see that the field $\left(\phi_{Y_{2}+\ldots+Y_{k}}^{1}\right)_{*} X$ is a member of $\mathcal{Y}$.
The vector field $\left(\varphi_{Y_{2}+\ldots+Y_{k}}^{1}\right)_{*} X$ is called the normal form of $X$. We will see that its linear part is still $A$, but the next terms in its Taylor development have an additional property given by the commutation with $B$. In the best cases, all the monomial terms of order 2 to $k$ are zero, which means that $X$, once pushed forward by the diffeomorphism $\varphi_{Y_{2}+\ldots+Y_{k}}^{1}$, is very close to its linear part. Then the dynamics of the flow of $X$ can be approached by the one of $A$. In the worst cases, e.g. if $B=0$, the theorem gives no information at all.

## 3 Proof of the main theorem

We grade the ring $\mathbb{R}\left[x_{1}, x_{2}, \ldots, x_{n}\right]$ by degree, i.e.

$$
\mathbb{R}\left[x_{1}, x_{2}, \ldots, x_{n}\right]=\bigoplus_{k \geqslant 0} E_{k},
$$

where $E_{k}$ is the space of homogenous polynomials of degree $k$. We define $E^{k}:=E_{1} \oplus \ldots \oplus E_{k}$ the vector space of polynomials $P$ of degree lower than $k$ such that $P(0)=0$.

The main idea in this proof is to associate both vector fields $X \in \mathcal{X}$ and diffeomorphisms $\phi \in \mathcal{G}$ with endomorphisms of $E^{k}, \widehat{X}$ and $\widetilde{\phi}$, which express their behaviour around 0 at order $k$. We therefore define two morphisms of vector spaces:

$$
\begin{aligned}
\wedge \mathcal{X} & \longrightarrow \operatorname{End}\left(E^{k}\right) \\
X & \longmapsto\left(P \in E^{k} \mapsto[X \cdot P]^{k}\right),
\end{aligned}
$$

and

$$
\begin{aligned}
\sim: \mathcal{G} & \longrightarrow \operatorname{End}\left(E^{k}\right) \\
\phi & \longmapsto\left(P \in E^{k} \mapsto[P \circ \phi]^{k}\right) .
\end{aligned}
$$

### 3.1 Analysis of the kernels

If $[X]^{k}=0, X \in \mathcal{X}$, then

$$
[X P]^{k}=\left[\sum_{i=1}^{n} X^{i} \partial_{i} P\right]^{k}=\sum_{i=1}^{n}\left[X^{i} \partial_{i} P\right]^{k}=\sum_{i=1}^{n}\left[\left[X^{i}\right]^{k} \partial_{i} P\right]^{k}=\left[[X]^{k} P\right]^{k}=0 .
$$

In the same way, if $[\phi]^{k}=0, \phi \in \mathcal{G}$, then

$$
\begin{aligned}
{[P \circ \phi]^{k}(x) } & =\left[P \circ\left([\phi]^{k}(x)+O\left(|x|^{k+1}\right)\right)\right]^{k}=\left[P\left([\phi]^{k}(x)\right)+O\left(|x|^{k+1}\right)\right]^{k} \\
& =\left[P \circ[\phi]^{k}\right]^{k}(x)=0,
\end{aligned}
$$

hence $[P \circ \phi]^{k}=0$. Moreover, when $P=\mathrm{id}, \widehat{X}(\mathrm{id})=[X]^{k}$ and $\widetilde{\phi}(\mathrm{id})=[\phi]^{k}$. Thus we have $\operatorname{Ker}^{\wedge}=\left\{X \in \mathcal{X},[X]^{k}=0\right\}$ and $\operatorname{Ker}{ }^{\sim}=\left\{\phi \in \mathcal{G},[\phi]^{k}=0\right\}$. We then conclude that the image of ${ }^{\wedge}$ and ${ }^{\sim}$ are determined by the $k$-th order development of their preimages.

### 3.2 Algebraic properties of ${ }^{\wedge}$ and

Proposition 2. We have:

1. $\forall \phi, \psi \in \mathcal{G}(\phi \circ \psi) \widetilde{ }=\widetilde{\psi} \circ \widetilde{\phi}$
2. $\forall \phi \in \mathcal{G}, \forall X \in \mathcal{X}, \phi_{*} X \in \mathcal{X}$ and $\left(\phi_{*} X\right)=\widetilde{\phi^{-1}} \circ \widehat{X} \circ \widetilde{\phi}$
3. $[X, Y]^{\wedge}=\widehat{X} \circ \widehat{Y}-\widehat{Y} \circ \widehat{X}$

Proof. 1. In fact,

$$
\begin{aligned}
(\phi \circ \psi)(x) & =[\phi]^{k}(\psi(x))+O\left(|\psi(x)|^{k+1}\right) \\
& =[\phi]^{k}\left([\psi]^{k}(x)+O\left(|x|^{k+1}\right)\right)+O\left(|x|^{k+1}\right) \\
& =[\phi]^{k} \circ[\psi]^{k}(x)+O\left(|x|^{k+1}\right),
\end{aligned}
$$

hence for all $P$ in $E_{k}$,

$$
(\phi \circ \psi) \tilde{)}(P)=\left[P \circ[\phi \circ \psi]^{k}\right]^{k}=\left[P \circ[\phi]^{k} \circ[\psi]^{k}\right]^{k}=\left[\left[P \circ[\phi]^{k}\right]^{k} \circ[\psi]^{k}\right]^{k}=\widetilde{\psi}(\widetilde{\phi}(P)) .
$$

2. Take $P \in E_{k}$, we have $\left(\phi_{*} X\right) P=X(P \circ \phi) \circ \phi^{-1}$, so

$$
\begin{aligned}
{\left[\left(\phi_{*} X\right) P\right]^{k} } & =\widetilde{\phi^{-1}}\left([X(P \circ \phi)]^{k}\right)=\widetilde{\phi^{-1}}\left(\sum_{i=1}^{n}\left[X^{i} \partial_{i}(P \circ \phi)\right]^{k}\right) \\
& =\widetilde{\phi^{-1}}\left(\sum_{i=1}^{n}\left[X^{i} L_{i}\left([P \circ \phi]^{k+1}\right)\right]^{k}\right)
\end{aligned}
$$

where $L_{i}: x_{1}^{j_{1}} \ldots x_{i}^{j_{i}} \ldots x_{n}^{j_{n}} \longmapsto j_{i} x_{1}^{j_{1}} \ldots x_{i}^{j_{i}-1} \ldots x_{n}^{j_{n}}$. Since $\forall i, X^{i}(0)=0$,

$$
\begin{aligned}
{\left[\left(\phi_{*} X\right) P\right]^{k} } & =\widetilde{\phi^{-1}}\left(\sum_{i=1}^{n}\left(\left[X^{i} \partial_{i}[P \circ \phi]^{k}\right]^{k}+\left[X^{i} \partial_{i}[P \circ \phi]_{k+1}\right]^{k}\right)\right) \\
& =\widetilde{\phi^{-1}}\left(\left[X[P \circ \phi]^{k}\right]^{k}\right)=\widetilde{\phi^{-1}} \circ \widehat{X} \circ \widetilde{\phi}(P)
\end{aligned}
$$

3. By the same argument as in 2, as $X(0)=0$,

$$
\begin{aligned}
\widehat{X Y}(P) & =[X(Y P)]^{k}=\left[X[Y P]^{k+1}\right]^{k}=\left[X[Y P]^{k}\right]^{k}+\left[X[Y P]_{k+1}\right]^{k} \\
& =\left[X[Y P]^{k}\right]^{k}=\widehat{X} \circ \widehat{Y}(P) .
\end{aligned}
$$

### 3.3 Image of the flow of a vector field

For $X \in \mathcal{X}$, we now consider its flow $\varphi_{X}: \mathcal{D} \subseteq \mathbb{R} \times \mathbb{R}^{n} \longrightarrow \mathbb{R}^{n}$. Since $\varphi_{X}(t, 0)=0$ is defined for all $t \in \mathbb{R}$, we have $\varphi_{X}^{1}=\varphi_{X}(1, \cdot)$ is defined on a neighbourhood of 0 , hence $\varphi_{X}^{1} \in \mathcal{G}$.

Proposition 3. We have $\widetilde{\varphi_{X}^{1}}=\exp (\widehat{X})$.
Proof. Note that $\operatorname{End}\left(E^{k}\right)$ is of finite dimension (with any norm on $\operatorname{End}\left(E^{k}\right)$ ), thus the ODE $\alpha^{\prime}(t)=\alpha(t) \circ \widehat{X}$ with initial condition $\alpha(0)=\mathbb{1}_{E^{k}}$ has a unique solution. The solution is exactly $\alpha(t)=\exp (t \widehat{X})$.

We can also note that $\partial_{t}\left(P \circ \varphi_{X}\right)=(X P) \circ \varphi_{X}$. We consider the Taylor developments of $\partial_{t}\left(P \circ \varphi_{X}\right)$ and $\left(P \circ \varphi_{X}\right)$ at 0 with respect to $x$ for each $t$ :

$$
\partial_{t}\left(P \circ \varphi_{X}\right)(t, x)=\sum_{|\nu| \leqslant k} \frac{1}{\nu!} \theta^{\nu}(t) x^{\nu}+O\left(|x|^{k+1}\right)
$$

and

$$
\left(P \circ \varphi_{X}\right)(t, x)=\sum_{|\nu| \leqslant k} \frac{1}{\nu!} \beta^{\nu}(t) x^{\nu}+O\left(|x|^{k+1}\right)
$$

where $\nu \in \mathbb{N}^{n}$ are multi-indices, and $\nu!=\prod_{i=1}^{n} \nu_{i}!$.
Then $\left(\beta^{\nu}\right)^{\prime}(t)=\theta^{\nu}(t)$, for $\beta^{\nu}(t)=\partial_{\nu}\left(P \circ \varphi_{X}\right)(t, 0)$ and

$$
\theta^{\nu}(t)=\partial_{\nu}\left(\partial_{t}\left(P \circ \varphi_{X}\right)\right)(t, 0)=\partial_{t}\left(\partial_{\nu}\left(P \circ \varphi_{X}\right)\right)(t, 0)=\frac{d}{d t} \beta^{\nu}(t)
$$

Hence we have $\partial_{t} \widetilde{\varphi_{X}^{t}}(P)=\widetilde{\varphi_{X}^{t}} \circ \widehat{X}(P)$, and $\varphi_{X}^{0}(P)=P$, so $\widetilde{\varphi_{X}^{t}}=\exp (t \widehat{X})$.

### 3.4 Conjugated operators

We define two more operators. For $V \in E n d\left(E^{k}\right)$, if $V$ is invertible, we define

$$
\begin{aligned}
A d_{V}: \operatorname{End}\left(E^{k}\right) & \longrightarrow \operatorname{End}\left(E^{k}\right) \\
M & \longmapsto V^{-1} \circ M \circ V .
\end{aligned}
$$

and for any $L \in \operatorname{End}\left(E^{k}\right)$,

$$
\begin{aligned}
a d_{L}: E n d\left(E^{k}\right) & \longrightarrow \operatorname{End}\left(E^{k}\right) \\
M & \longmapsto[M, L]=M \circ L-L \circ M .
\end{aligned}
$$

Note that $A d_{V} \in G L\left(E n d\left(E^{k}\right)\right) \subseteq \operatorname{End}\left(\operatorname{End}\left(E^{k}\right)\right)$, and that $a d_{L} \in \operatorname{End}\left(\operatorname{End}\left(E^{k}\right)\right)$.
Proposition 4. $\forall L \in E n d\left(E^{k}\right), A d_{\exp L}=\exp \left(a d_{L}\right)$.
Proof. Let $\alpha(t)=A d_{\exp (t L)}$, then

$$
\alpha^{\prime}(t) M=-L \circ(\alpha(t) M)+(\alpha(t) M) \circ L=\left(a d_{L} \circ \alpha(t)\right) M
$$

Thus $\alpha(t)=\exp \left(a d_{t L}\right)$, so $A d_{\exp L}=\exp \left(a d_{L}\right)$.

### 3.5 Proof of the theorem

The commutative statement of the $k$-th development of vector fields with the field $B$ is now well characterised by the commutativity of their image under ${ }^{\wedge}$ by the third assumption of proposition 2 . We'll now prove the theorem by induction, with the help of ${ }^{\wedge}$ and ${ }^{\sim}$. Suppose we already have $Y_{i} \in \mathcal{Y}_{i}, 2 \leqslant i \leqslant k-1$, such that $\left[\left(\varphi_{Z}^{1}\right)_{*} X-A\right]^{k-1}$ commutes with $B$ and $\left(\phi_{Z}^{1}\right)_{*} X \in \mathcal{Y}$, where $Z=\sum_{2 \leqslant i \leqslant k-1} Y_{i}$.

By the second assumption of proposition 2 and propositions 3 and 4 , we have

$$
\begin{aligned}
\left(\left(\varphi_{Z}^{1}\right)_{*} X\right) & =\widetilde{\left(\varphi_{Z}^{1}\right)^{-1}} \circ \widehat{X} \circ \widetilde{\varphi_{X}^{1}}=\exp (-\widehat{Z}) \circ \widehat{X} \circ \exp (\widehat{Z}) \\
& =A d_{\exp \widehat{Z}}(\widehat{X})=\exp \left(a d_{\widehat{Z}}\right) \widehat{X}
\end{aligned}
$$

Indeed, $\forall Y \in \mathcal{Y}^{k},[Z, Y] \in \mathcal{Y}^{k}$ so $a d_{\widehat{Z}}(\widehat{Y})=[\widehat{Y}, \widehat{Z}]=[Y, Z]^{\wedge}$, and from the kernel of $\widehat{\wedge}$, we know that $\left(\mathcal{Y}^{k}\right)^{\wedge}=\widehat{\mathcal{Y}} \subseteq \operatorname{End}\left(E^{k}\right)$. Then $a d_{\widehat{Z}}$ preserves $\widehat{\mathcal{Y}} \subseteq E n d\left(E^{k}\right)$, and so does $\exp \left(a d_{\widehat{Z}}\right)=A d_{\exp \widehat{Z}}$.

By the induction hypotheses and the preservation argument for dimension $k-1$, we have $\left(\left(\phi_{Z}^{1}\right)_{*} X\right)=A d_{\exp \widehat{Z}}(\widehat{X})=\widehat{A}+\widehat{N}+\widehat{R_{k}}$, where $N \in \mathcal{Y}^{k-1}$ has no linear term and commutes with $B$, and $R_{k} \in \mathcal{Y}_{k}$. For all $Y_{k} \in \mathcal{Y}_{k}$, note that $Z$ consists of monomials with degree at least 2 , which leads to $\widehat{Z} \circ \widehat{Y}_{k}=\widehat{Y}_{k} \circ \widehat{Z}=0$. Hence we have $\exp \left(\widehat{Z}+\widehat{Y}_{k}\right)=\exp (\widehat{Z}) \circ \exp \left(\widehat{Y}_{k}\right)$. We then have equations:

$$
\begin{aligned}
\exp (-\widehat{Z} & \left.-\widehat{Y}_{k}\right) \circ \widehat{X} \circ \exp \left(\widehat{Z}+\widehat{Y}_{k}\right) \\
& =\exp \left(-\widehat{Y}_{k}\right) \circ\left(\widehat{A}+\widehat{N}+\widehat{R_{k}}\right) \circ \exp \left(\widehat{Y}_{k}\right) \\
& =\left(\mathrm{id}-\widehat{Y_{k}}\right) \circ\left(\widehat{A}+\widehat{N}+\widehat{R_{k}}\right) \circ\left(\mathrm{id}+\widehat{Y}_{k}\right), \quad \text { since } \widehat{Y}_{k} \circ \widehat{Y}_{k}=0 \\
& =\widehat{A}+\widehat{N}+\widehat{R_{k}}+\widehat{A} \circ \widehat{Y}_{k}-\widehat{Y_{k}} \circ \widehat{A} .
\end{aligned}
$$

We already proved that $\left(\phi_{Z+Y_{k}}^{1}\right)_{*} X$ is a normal form of order k if and only if $\left[\left(\left(\phi_{Z+Y_{k}}^{1}\right)_{*} X\right) \hat{}-\widehat{A}, \widehat{B}\right]=0$. By the computation above, it's equivalent to

$$
a d_{\widehat{B}}\left(\widehat{R_{k}}-a d_{\widehat{A}}\left(\widehat{Y}_{k}\right)\right)=0
$$

The following proposition implies $a d_{\widehat{B}} \circ a d_{\widehat{A}}\left(\widehat{\mathcal{Y}_{k}}\right)=a d_{\widehat{B}}\left(\widehat{\mathcal{Y}_{k}}\right)$, hence the equation has a solution $Y_{k} \in \mathcal{Y}_{k}$, which finishes the proof.

Proposition 5. $\widehat{\mathcal{Y}_{k}}=\left(\widehat{\mathcal{Y}_{k}} \cap \operatorname{ker}\left(a d_{\widehat{B}}\right)\right)+a d_{\widehat{A}}\left(\widehat{\mathcal{Y}_{k}}\right)$.

Proof. We give a proof only in the case where $A$ is diagonalisable and $B=A$; the general case is quite more difficult. For this case, note that $\widehat{A}=\widehat{B}$ is diagonalisable. For simplicity, we omit the hats in the rest of the proof.

In an eigenbasis of $A$ (of eigenvalues $\left(\lambda_{i}\right)$ ), we take $M=\left(m_{i j}\right) \in \operatorname{End}(V)$ such that $[A, M] \in \operatorname{ker}\left(a d_{B}\right)=k e r\left(a d_{A}\right)$. This condition, written in coordinates, gives

$$
\forall i, j, 0=[[M, A], A]_{i j}=\left(\lambda_{j}-\lambda_{i}\right)^{2} m_{i j},
$$

which implies $\left(\lambda_{j}-\lambda_{i}\right) m_{i j}=0=[M, A]_{i j}$. Hence, we have

$$
\operatorname{ker}\left(a d_{A}\right) \cap i m\left(a d_{A}\right)=0 .
$$

Moreover, $\operatorname{dim}\left(\operatorname{ker}\left(a d_{A}\right)\right)+\operatorname{dim}\left(\operatorname{im}\left(a d_{A}\right)\right)=\operatorname{dim}(\operatorname{End}(V))$. Thus we arrived to the equation.

Remark 2. When $B$ is adjoint of $A$ for the inner product $<,>$, the same proof applies : if $[[M, A], B]=0$,

$$
\begin{aligned}
0 & =<[[M, A], B], M>=<[M, A] B>-<B[M, A], M> \\
& =<[M, A], M A>-<[M, A], A M>=\|[M, A]\|^{2}
\end{aligned}
$$

so $[M, A]=0$ and $\operatorname{ker}\left(a d_{A}\right) \cap i m\left(a d_{A}\right)=0$.

## 4 Link with the Poincaré-Dulac theorem

In this section, we show that the main theorem includes the following one, exposed in [1] :

Theorem 6. (Poincaré-Dulac) Let $\mathcal{X}^{\prime}=\left\{X \in \Gamma\left(T \mathbb{C}^{n}\right)\right.$, holomorphic, such that $X(0)=0\}, \mathcal{G}^{\prime}$ the group of local diffeomorphisms of $\mathbb{C}^{n}$ that fix 0 , $X \in \mathcal{X}^{\prime}, A=[X]_{1}$ its linear part, $\lambda_{1}, \ldots, \lambda_{n}$ the complex eigenvalues of $A,\left(e_{1}, \ldots e_{n}\right)$ the eigenbasis of $A$ in $\mathbb{C}^{n}$, and $k \geqslant 2$. Then

$$
\exists \phi \in \mathcal{G}^{\prime}, \exists\left(\alpha_{m, s}\right) \in \mathbb{C}^{\mathcal{R}}, \phi_{*} X(x)=A x+\sum_{(m, s) \in \mathcal{R}} \alpha_{m, s} x^{m} e_{s}+O\left(|x|^{k+1}\right),
$$

where $\mathcal{R}=\left\{(m, s) \in \mathbb{N}^{n} \times \llbracket 1, n \rrbracket, \lambda^{m}=\lambda_{s}\right.$ and $\left.2 \leqslant|m| \leqslant k\right\}$ and $x^{m}=\prod_{i=1}^{n} x_{i}^{m_{i}}$.

The last expression is the normal form of $X$. The monomials of the form $x^{m} e_{s}$, with $(m, s)$ in $\mathcal{R}$, are called resonant terms. The dynamics of the flow strongly depends on $\mathcal{R}$, as we shall see in further examples. Thus this theorem tells which terms can be removed without changing the behaviour of $\varphi_{X}$.

Remark 3. The main theorem applies in $\mathbb{R}^{n}$, but this one is only valid for holomorphic vector fields in $\mathbb{C}^{n}$. Thus, in the proof, we identify $\mathbb{C}^{n}$ with $\mathbb{R}^{2 n}$ through an isomorphism $\Phi$.

In fact, the main theorem shows the similarity between Poincaré-Dulac and Poincaré-Birkhoff normal form theorems by reformulating both of them in a commmon context.

Proof. We just apply the main theorem in the case $B=A_{s}$.
We set $\mathcal{X}=\left\{X \in \Gamma\left(T \mathbb{R}^{2 n}\right), X(0)=0\right\}$ and $\mathcal{Y}=\Phi_{*}\left(\mathcal{X}^{\prime}\right)$. As the Lie bracket of holomorphic vector fields is an holomorphic vector field, $\mathcal{Y}$ is a sub-algebra of $\mathcal{X}$. We also have $\left[\Phi^{*} X\right]_{1}=\Phi^{*}[X]_{1}=\Phi^{*} A$, and $\Phi^{*} B$ is the diagonalisable part of $\Phi^{*} A$, so we can apply the main theorem.

We get $\phi=\Phi^{*}\left(\varphi_{Y_{2}+\cdots+Y_{k}}^{1}\right) \in \mathcal{G}^{\prime}$ such that $\left[\Phi_{*}\left(\phi_{*} X-A\right)\right]^{k}$ commutes with $\Phi_{*}(B)$, which is equivalent to the commutation of $\left[\phi_{*} X-A\right]^{k}$ and $B$.

We write the Taylor development of $\phi_{*} X$ :

$$
\exists\left(\alpha_{m, s}\right) \in \mathbb{C}^{\mathbb{N}^{n} \times \llbracket 1, n \rrbracket}, \phi_{*} X(x)=A x+\sum_{\substack{(m, s) \\ 2 \leqslant|m| \leqslant k}} \alpha_{m, s} x^{m} e_{s}+O\left(|x|^{k+1}\right)
$$

As $B(x)=\sum_{s=1}^{n} \lambda_{s} x_{s} e_{s}$, we compute :

$$
\begin{aligned}
0 & =\left[\left[\phi_{*} X-A\right]^{k}, B\right](x) \\
& =\sum_{\substack{(m, s) \\
2 \leqslant|m| \leqslant k}} \alpha_{m, s} B(x)^{m} e_{s}-B\left(\sum_{\substack{(m, s) \\
2 \leqslant|m| \leqslant k}} \alpha_{m, s} x^{m} e_{s}\right)+O\left(|x|^{k+1}\right) \\
& =\sum_{\substack{(m, s) \\
2 \leqslant|m| \leqslant k}} \alpha_{m, s} \lambda^{m} x^{m} e_{s}-\sum_{\substack{(m, s) \\
2 \leqslant|m| \leqslant k}} \alpha_{m, s} x^{m} \lambda_{s} e_{s}+O\left(|x|^{k+1}\right) \\
& =\sum_{\substack{(m, s) \\
2 \leqslant|m| \leqslant k}} \alpha_{m, s}\left(\lambda^{m}-\lambda_{s}\right) x^{m} e_{s}+O\left(|x|^{k+1}\right)
\end{aligned}
$$

The family $\left(x^{m} e_{s}\right)_{1 \leqslant|m| \leqslant k, 1 \leqslant s \leqslant n}$ is a base of $E^{k}$, so all the terms of the sum are zero. If $(m, s) \in \mathcal{R}$, as $\lambda^{m}-\lambda_{s} \neq 0$, we conclude that $\alpha_{m, s}=0$, which gives us the expected result.

## 5 A direct proof of Poincaré-Dulac theorem

As the main theorem is quite abstract and more complex than PoincaréDulac theorem, we give an elementary proof of the latest in the case of a diagonalisable linear part $A=B$. This proof shows how to choose the morphism $\phi$. We once again use an induction on $k$. The case $k=1$ is trivial. Let $k \geqslant 2$ such that the theorem holds for $k-1$. We know that
$\exists \phi \in \mathcal{G}^{\prime}, \exists\left(\alpha_{m, s}\right) \in \mathbb{C}^{\mathcal{R}}, \phi_{*} X(x)=A x+\sum_{(m, s) \in \mathcal{R}} \alpha_{m, s} x^{m} e_{s}+v(x)+O\left(|x|^{k+1}\right)$,
with $v$ a homogeneous polynomial of degree $k$ containing no resonant term. We want to find another a homogeneous polynomial $h$ of degree $k$ such that the change of variables $y=x-h(x)$ leads to

$$
\phi_{*} X(y)=A y+\sum_{(m, s) \in \mathcal{R}} \alpha_{m, s} y^{m} e_{s}+O\left(|y|^{k+1}\right) .
$$

We compute

$$
\begin{aligned}
\phi_{*} X(y) & =\phi_{*} X(x-h(x))=\phi_{*} X(x)-d_{x}\left(\phi_{*} X\right)(h(x))+O\left(|x|^{2 k}\right) \\
& =A x+\sum_{(m, s) \in \mathcal{R}} \alpha_{m, s} x^{m} e_{s}+v(x)-\partial_{x} h A x+O\left(|x|^{k+1}\right) \\
& =A y+A h(x)+\sum_{(m, s) \in \mathcal{R}} \alpha_{m, s} y^{m} e_{s}+v(x)-\partial_{x} h A x+O\left(|x|^{k+1}\right) .
\end{aligned}
$$

Thus we get the good result if and only if $v(x)=\partial_{x} h A x-A h(x)=: L_{A} h(x)$. The operator $L_{A}$ is linear, so we can decompose

$$
v(x)=\sum_{\substack{(m, s) \notin \mathcal{R} \\|m|=k}} \alpha_{m, s} x^{m} e_{s}
$$

and look for a solution of each equation $L_{A} h(x)=x^{m} e_{s}$. But

$$
\begin{aligned}
L_{A}\left(x^{m} e_{s}\right) & =\sum_{i=1}^{n} \partial_{i} x^{m} e_{s} A x_{i}-A x^{m} e_{s} \\
& =\sum_{i=1}^{n} m_{i} \frac{x^{m}}{x_{i}} e_{s} x_{i}-\lambda_{s} x^{m} e_{s}=\left(\lambda^{m}-\lambda_{s}\right) x^{m} e_{s}
\end{aligned}
$$

The $\lambda^{m}-\lambda_{s}$ are different from zero for $(m, s) \notin \mathcal{R}$, so we just have to take

$$
h(x)=\sum_{\substack{(m, s) \notin \mathcal{R} \\|m|=k}} \frac{\alpha_{m, s}}{\lambda^{m}-\lambda_{s}} x^{m} e_{s} .
$$

Finally, the change of variables $\psi(x)=y=x-h(x)$ is a local diffeomorphism, and $\psi_{*} \phi_{*} X$ is the normal form of $X$ at order $k$, which concludes the proof.

Remark 4. Note that the last computations are the same in the two proofs : indeed, $L_{A}(h)$ is equal to the bracket of $h$ with $B$ in the case $B=A_{s}$.

## 6 Examples

In this section, we just study a few examples to understand the link between the previous theorems and the dynamics of the flow.

### 6.1 A system with only one resonance

Let $p, q \geqslant 2$ integers, $c \in \mathbb{R} \backslash\{0\}$, and $X:(x, y) \mapsto\left(x, p y+c x^{q}\right)$ a holomorphic vector field of $\mathbb{C}^{2}$. Its linear part is $A=\left(\begin{array}{ll}1 & 0 \\ 0 & p\end{array}\right)$. The dynamical systems associated to $A$ and $X$ are respectively

$$
\left\{\begin{array} { l } 
{ \frac { d } { d t } x = x } \\
{ \frac { d } { d t } y = p y }
\end{array} \quad \text { and } \quad \left\{\begin{array}{l}
\frac{d}{d t} x=x \\
\frac{d}{d t} y=p y+c x^{q}
\end{array}\right.\right.
$$

These systems can be solved explicitly. The first one has solutions of the form $x(t)=x_{0} e^{t}, y(t)=y_{0} e^{p t}$, which gives a trajectory $y(x)=y_{0}\left(\frac{x}{x_{0}}\right)^{p}$.


Figure 1: The trajectories of $\varphi_{A}$ in the case $p=2$, with $c=1$. They all converge at 0 , and three trajectories (including the one staying at 0 ) can be joined to form the $C^{\infty}$ colored curbs.

For the second one, the solution depends on the values of $p$ and $q$.

- If $p=q$, we have $x(t)=x_{0} e^{t}$, and $y(t)=\left(y_{0}+c x_{0}^{p} t\right) e^{p t}$,
so $y(x)=y_{0}\left(\frac{x}{x_{0}}\right)^{p}+c x^{p} \log \left(\frac{x}{x_{0}}\right)$.
- If $p \neq q$, we have $x(t)=x_{0} e^{t}$, and $y(t)=\left(y_{0}-\frac{c x_{0}^{q}}{q-p}\right) e^{p t}+\frac{c x_{0}^{q}}{q-p} e^{q t}$, so $y(x)=\left(y_{0}-\frac{c x_{0}^{q}}{q-p}\right)\left(\frac{x}{x_{0}}\right)^{p}+\frac{c}{q-p} x^{q}$.

Here, as $\lambda_{1}=1$ and $\lambda_{2}=p$, the only resonance is $\mathcal{R}=\{(m, s)\}=$ $\{((p, 0), 2)\}$. The resonant term $x^{p} e_{y}$ is non-zero only in the case $p=q$. Thus Poincaré-Dulac theorem states that $X$ is locally isomorphic to $A$ at order $k$ for all $k \geqslant 2$ whenever $p \neq q$. Indeed, the holomorphic application

$$
\begin{aligned}
\phi: \mathbb{C}^{2} & \longrightarrow \mathbb{C}^{2} \\
(x, y) & \longmapsto\left(x, y+\frac{c}{q-p} x^{q}\right)
\end{aligned}
$$

is a local diffeomorphism, and $\phi_{*} A=X$.


Figure 2: The trajectories of $\varphi_{X}$
Figure 3: The trajectories of $\varphi_{X}$ for for $p=q=2$. They are not $C^{2}$ at $0 . p=2$ and $q=3$. They form $C^{\infty}$ curbs.

At contrary, in the case $p=q$, we can find a $C^{q-1}$-diffeomorphism

$$
\begin{aligned}
\phi: \mathbb{C}^{2} & \longrightarrow \mathbb{C}^{2} \\
(x, y) & \longmapsto\left(x, y+c x^{p} \log x\right)
\end{aligned}
$$

but there is no $C^{q}$-diffeomorphism sending $\varphi_{A}$ on $\varphi_{X}$. Indeed, we can join 3 trajectories of $\varphi_{A}$ (the ones passing at $\left(x_{0}, y_{0}\right),(0,0)$ and $\left(-x_{0},(-1)^{p} y_{0}\right)$ respectively) to make the $C^{\infty}$-curb $\left\{\left(x, y_{0}\left(\frac{x}{x_{0}}\right)^{p}\right)\right\}$, but that's not possible with $\varphi_{X}$ because the function $y(x)$ written above is not $C^{p}$ at 0 . We then use the proposition below :

Proposition 7. With the same notations as before, let $\phi \in \mathcal{G} \mathcal{Y}$ and $X, Y \in \mathcal{Y}$ such that $\phi_{*} X=Y$. If the trajectories of $\varphi_{X}$ can be joined to form curbs $C^{k}$ at 0 , then the trajectories of $\varphi_{Y}$ can be joined to form curbs $C^{k}$ at 0 too.
Remark 5. As the trajectories are solutions to $\frac{d}{d t} x(t)=Y(x(t))$, the trajectories are $C^{\infty}$ at any regular point.

Proof. Let $c:]-\varepsilon, \varepsilon\left[\mapsto \mathbb{R}^{n}\right.$ a curb following trajectories of $\varphi_{X}$, i.e. such that $\forall \theta \in]-\varepsilon, \varepsilon\left[, \frac{d}{d \theta} c(\theta)\right.$ is colinear to $X(c(\theta))$. We assume that $c(0)=0$ and $c$ is $C^{k}$ at 0 . Then $\phi \circ c$ follows trajectories of $Y$ because

$$
\forall \theta \in]-\varepsilon, \varepsilon\left[, \frac{d}{d \theta} \phi \circ c(\theta)=d \phi_{c(\theta)} \frac{d}{d \theta} c(\theta)\right.
$$

is colinear to $Y(c(\theta))=\phi_{*} X(c(\theta))=d \phi_{c(\theta)} X(c(\theta))$.

Remark 6. The proposition remains true in $\mathbb{C}^{n}$ with holomorphic vector fields, using the same argument as in Poincaré-Dulac theorem.

### 6.2 Harmonic oscillator

We now study a harmonic oscillator with a non-linear term, of the form

$$
\left\{\begin{array}{l}
\frac{d}{d t} x=y \\
\frac{d}{d t} y=-x+c x^{a} y^{b}
\end{array}\right.
$$

We know that the solutions of the linear system are of the form $x(t)=$ $c_{1} e^{i t}+c_{2} e^{-i t}, y(t)=c_{1} e^{i t}-c_{2} e^{-i t}$, hence $|x|^{2}+|y|^{2}=2\left(\left|c_{1}\right|^{2}+\left|c_{2}\right|^{2}\right)$ is constant, so the trajectories are circles.

Here, $A=\left(\begin{array}{cc}0 & 1 \\ -1 & 0\end{array}\right)$, so $\lambda_{1}=i$ and $\lambda_{2}=-i$. Hence

$$
\mathcal{R}=\bigcup_{k \geqslant 0}\{((k+1, k), 1),((k, k+1), 2)\} .
$$

Consequently, the system above is resonant if and only if $b=a+1$. When multiplying the second equation by $y$, we get

$$
y \dot{y}=-x \dot{x}+c x^{a} y^{b+1},
$$

so

$$
\frac{1}{2} \frac{d}{d t}\left(|x|^{2}+|y|^{2}\right)=x \dot{x}+y \dot{y}=c x^{a} y^{b+1}
$$

If $a$ is even and $b=a+1, x^{a} \dot{x}^{b+1}=(x \dot{x})^{a} \dot{x}^{2} \geqslant 0$ and this term is different from zero (except at $x=0$ or $y=0$ ), so the radius $r=\sqrt{|x|^{2}+|y|^{2}}$ depends monotonously on time at a finite order, increasing if $\Re(c)>0$ and decreasing if $\Re(c)<0$, and the trajectories are spirals.

On the other hand, when $b \neq a+1$ the Poincaré-Dulac theorem implies that the trajectories remain close to cycles at any order $k$, as they are $C^{k}$ diffeomorph to the circles of the linear system at order $k$.

To make it more clear, define $D(x, y)=|x(2 \pi)-x(0)|^{2}+|y(2 \pi)-y(0)|^{2}$ to measure the evolution of the coordinates after a time $2 \pi$. In the linear case, $\varphi_{A}$ is $2 \pi$-periodic, so $D(x, y)=0$. With a non-linear term such that $b \neq a+1$,
using Poincaré-Dulac theorem, $\forall k, D(x, y)=o\left(r^{k}\right)$. Finally, when $b=a+1$, as the variations of $r^{2}$ are of order $a+b+1=2 a+2, D(x, y)=\Theta\left(r^{a+1}\right)$.

We now understand better the choice of the word resonance: a monomial term is resonant when he corresponds to a perturbation of the linear system that can affect the properties of the dynamics around the origin.

### 6.3 Coupled oscillators

We now study a system composed of two harmonic oscillators coupled through their position :

$$
\left\{\begin{array}{l}
\dot{x}_{1}=\omega_{1} y_{1}+c x_{2} \\
\dot{y}_{1}=\omega_{1} x_{1} \\
\dot{x}_{2}=\omega_{2} y_{2}+c x_{1} \\
\dot{y}_{2}=\omega_{2} x_{2}
\end{array}\right.
$$

with $\omega_{1}>\omega_{2}>0$. Of course, each oscillator has its own resonances, as in the previous example. What we want to know is whether they are non-trivial resonances caused by the interaction between the oscillators. Let's compute the eigenvalues of $A$ :

$$
\begin{aligned}
\operatorname{det}(A-u I) & =\operatorname{det}\left(\begin{array}{cccc}
-u & \omega_{1} & c & 0 \\
-\omega_{1} & -u & 0 & 0 \\
c & 0 & -u & \omega_{2} \\
0 & 0 & -\omega_{2} & -u
\end{array}\right) \\
& =\left(u^{2}+\omega_{1}^{2}\right)\left(u^{2}+\omega_{2}^{2}\right)-c^{2} u^{2} \\
& =u^{4}+\left(\omega_{1}^{2}+\omega_{2}^{2}-c^{2}\right) u^{2}+\omega_{1}^{2} \omega_{2}^{2} .
\end{aligned}
$$

For $c$ sufficiently small, the eigenvalues are

$$
\lambda_{1,2}=i\left(\frac{\omega_{1}^{2}+\omega_{2}^{2}-c^{2} \pm \sqrt{\left(\omega_{1}^{2}+\omega_{2}^{2}-c^{2}\right)^{2}-4 \omega_{1}^{2} \omega_{2}^{2}}}{2}\right)^{\frac{1}{2}}
$$

and their complex conjugates. The non-trivial resonances are the ones of the form $a \lambda_{1}+b \lambda_{2}=0$, with $(a, b) \in \mathbb{N}^{2} \backslash\{(0,0)\}$. The function $f(c)=\frac{\lambda_{1}}{\lambda_{2}}(c)$ is continuous, monotonic, defined on $\left[0, \sqrt{\omega_{1}^{2}+\omega_{2}^{2}}\right]$, and reaches $\frac{\omega_{1}^{2}}{\omega_{2}^{2}}$ at 0 and 1 at $\sqrt{\omega_{1}^{2}+\omega_{2}^{2}}$, so $f$ reaches rational values on an infinite countable set of values of $c$.

As a conclusion, non-trivial resonant terms exist only for specific values of $c, \omega_{1}$ and $\omega_{2}$. We can see the eigenvalues as modified frequences, because $\lambda_{1} \longrightarrow_{c \rightarrow 0} \omega_{1}$, and $\lambda_{2} \longrightarrow_{c \rightarrow 0} \omega_{2}$. The resonances appear whenever the ratio of these frequences is rationnal.

## 7 Generalisation to a family of vector fields

It's very natural to consider the regularity of the normal forms of a family of vector fields. That's to say if we have a family of vector fields $X_{\lambda}$ singular at 0 parameterised by $\lambda \in \Lambda$, and depends on $\lambda$ with some regularity, then we want to know if there's some family $\left(Y_{\lambda}^{k}\right)$ of normal forms of the $X_{\lambda}$ with the same regularity on $\lambda$. We're going to formalise the problem and give it an affirmative answer.

Definition 1. Assume $\Lambda$ is a Banach space, we say the family of vector fields $X_{\lambda}$ depends on $\lambda C^{r}$ regularly, if the map

$$
\begin{array}{rlc}
\Lambda \times U & \longrightarrow & \mathbb{R}^{n} \\
(\lambda, x) & \longmapsto & X_{\lambda}(x)
\end{array}
$$

is $C^{r}$ smooth as a map from an open subset of the product Banach space $\Lambda \times \mathbb{R}^{n}$ to $\mathbb{R}^{n}$. Here $U \ni 0$ is an open set of $\mathbb{R}^{n}$ and we regard $X_{\lambda} \in \Gamma(T U)$ as a map $X_{\lambda}: U \rightarrow \mathbb{R}^{n}$ by the natural identification $T \mathbb{R}^{n} \approx \mathbb{R}^{n+n}$ mentioned in the beginning.

The answer to the problem is stated here.
Theorem 8. Let $\Lambda$ be a Banach space, $X_{\lambda} a C^{r}$ family of vector fields, $A \in \mathcal{Y}_{1}$ the linear part of $X_{0}$ at 0 , and we choose $B$ as in the main theorem. Then, there exists a $C^{r}$ family of vector fields $Y_{\lambda}^{k} \in \mathcal{Y}^{k}$, such that $Y_{0}^{k}$ has no linear term, and there exists an open set $V \subseteq \Lambda$, such that $\forall \lambda \in V,\left[\left[\left(\phi_{Y_{\lambda}^{k}}^{1}\right)_{*} X_{\lambda}-A\right]^{k}, B\right]=0$.

Proof. Similarly to the proof of the main theorem, we prove it by induction on $k$. Suppose that we have built $C^{r}$ vector fields $Y_{\lambda}^{k-1}, k \geqslant 2$. We then, by the same computation, get the equation:

$$
a d_{\widehat{B}}\left(\widehat{R_{\lambda}}\right)-a d_{\widehat{B}} \circ a d_{\widehat{A_{\lambda}}}\left(\widehat{Y_{\lambda}}\right)=0
$$

where $R_{\lambda}$ and $A_{\lambda}$ are the homogenous term of degree $k$ and the linear term of $\left(\phi_{Y_{\lambda}^{k-1}}^{1}\right)_{*} X_{\lambda}$ respectively.
The induction hypotheses implies that $R_{\lambda}$ and $A_{\lambda}$ are $C^{r}$ families. By proposition 5 , we have $a d_{\widehat{B}} \circ a d_{\widehat{A}}: \widehat{\mathcal{Y}_{k}} \longrightarrow a d_{\widehat{B}}\left(\widehat{\mathcal{Y}_{k}}\right)$ is surjective. We may choose a $K \subseteq \widehat{\mathcal{Y}_{k}}$ as the complementary of its kernal, thus

$$
a d_{\widehat{B}} \circ a d_{\widehat{A}}: K \longrightarrow a d_{\widehat{B}}\left(\widehat{\mathcal{Y}_{k}}\right)
$$

is an isomorphism. By the regularity of $A_{\lambda}, \exists V \subseteq \Lambda$ open set, such that $\forall \lambda \in V, a d_{\widehat{B}} \circ a d_{\widehat{A_{\lambda}}}: K \longrightarrow a d_{\widehat{B}}\left(\widehat{\mathcal{Y}_{k}}\right)$ is an isomorphism. We denote

$$
\theta_{\lambda}=\left(a d_{\widehat{B}} \circ a d_{\widehat{A_{\lambda}}}\right)^{-1}: a d_{\widehat{B}}\left(\widehat{\mathcal{Y}_{k}}\right) \longrightarrow K,
$$

then $\theta_{\lambda}$ is $C^{r}$ on $\lambda$. Take $Y_{\lambda}=-\theta_{\lambda} \circ a d_{\widehat{B}}\left(R_{\lambda}\right)$, which is a $C^{r}$ family of vector fields and solves the equation.
We finally need to set the initial condition, i.e. to show the existence of a $C^{r}$ family of vector fields $L_{\lambda} \in \mathcal{Y}_{1}$, such that $L_{0}=0$ and

$$
\forall \lambda \in V,\left[\exp \left(-\widehat{L_{\lambda}}\right) \widehat{A_{\lambda}} \exp \left(\widehat{L_{\lambda}}\right)-\widehat{A}, \widehat{B}\right]=0
$$

Suppose $K \subseteq \widehat{\mathcal{Y}_{1}}$ a complementary of $\operatorname{ker}\left(a d_{\widehat{B}} \circ a d_{\widehat{A}}\right)$. Consider the map

$$
\begin{aligned}
F: K \times \Lambda & \longrightarrow a d_{\widehat{B}}\left(\widehat{\mathcal{Y}_{1}}\right) \\
(L, \lambda) & \longmapsto a d_{\widehat{B}}\left(\exp (-\widehat{L}) \widehat{A_{\lambda}} \exp (\widehat{L})-\widehat{A}\right) .
\end{aligned}
$$

We have $\partial_{L} F(0,0)=a d_{\widehat{B}} \circ a d_{\widehat{A}}$, which is an isomorphism from $K \approx T_{0} K$ to $a d_{B}\left(\widehat{\mathcal{Y}_{1}}\right) \approx T_{0}\left(a d_{B}\left(\widehat{\mathcal{Y}_{1}}\right)\right)$. Then by the implicit function theorem, we have a $C^{r}$ family of linear maps $\widehat{L_{\lambda}}$ which lifts back to a $C^{r}$ family of vector fields $L_{\lambda}$.

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