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EFFECTS OF VISCOSITY ON WATER WAVES

SÉMINAIRE DOCTORAL DU LAMFA - UNIVERSITÉ PICARDIE JULES VERNE

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Free-surface Navier-Stokes equation

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \frac{1}{\text{Re}} \Delta \mathbf{u} + \mathbf{y}$$
$$\nabla \cdot \mathbf{u} = 0$$

with **stress-free** boundary conditions on the interface $\Gamma_s(t)$,

$$p \mathbf{n} - \frac{2}{\text{Re}} \left[\nabla \mathbf{u} + (\nabla \mathbf{u})^t \right] \cdot \mathbf{n} = 0$$

and **Navier** conditions at the bottom Γ_b ,

$$\mathbf{u} \cdot \mathbf{n} = 0$$
$$\cdot \left[\nabla \mathbf{u} + (\nabla \mathbf{u})^t \right] \cdot \mathbf{n} = 0$$

Weak formulation

Function space

$$\mathbf{H}_{\Gamma_b}^1(\Omega_t) = \left\{ \mathbf{v} \in (H^1(\Omega_t))^2 : \mathbf{v} \cdot \mathbf{n} = 0 \text{ on } \Gamma_b \right\}$$

We **do not** assume **the** incompressibility, $\nabla \cdot \mathbf{u} = 0$, directly in the function space as it would not work in finite element.

Find $\mathbf{u} \in \mathcal{C}^1([0, T]; \mathbf{H}_{\Gamma_b}^1(\Omega_t))$ and $p \in L^\infty([0, T], L^2(\Omega_t))$ such that

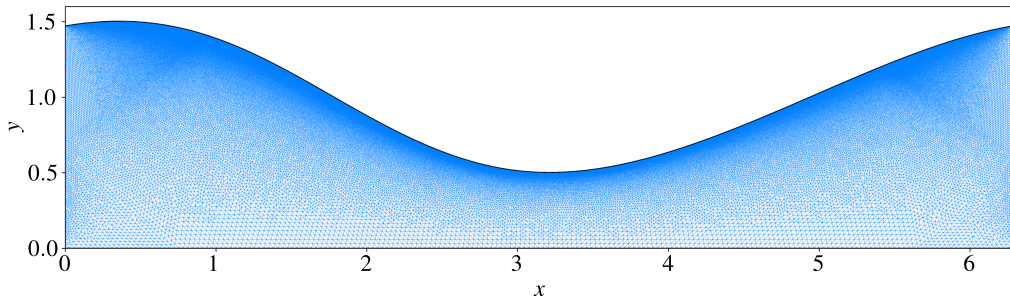
$$\int_{\Omega_t} \mathbf{v} \cdot \partial_t \mathbf{u} + \mathbf{v} \cdot (\mathbf{u} \cdot \nabla) \mathbf{u} + \frac{2}{\text{Re}} \mathbb{S}(\mathbf{v}) : \mathbb{S}(\mathbf{u}) - p \nabla \cdot \mathbf{v} + q \nabla \cdot \mathbf{u} - \mathbf{v} \cdot \mathbf{g} = 0$$

for all $\mathbf{v} \in \mathbf{H}_{\Gamma_b}^1(\Omega_t)$ and $q \in L^2(\Omega_t)$, at all time $t \in (0, T)$.

Finite Element

We use FreeFem (c++ finite element library,  [Hecht, 2012](#)) for

- mesh generation and advection
- matrices generation
- Multi-threading using a PETSc interface



Initial mesh with 4 000 points on the interface, leading to $\approx 200\,000$ triangles, $\approx 10^6$ degrees of freedom.

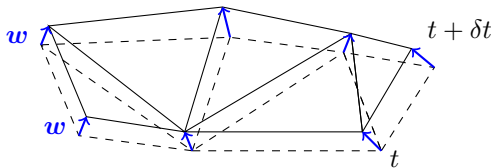
Mesh advection

Let w the **mesh velocity**. It is computed at each time step solving the following problem numerically

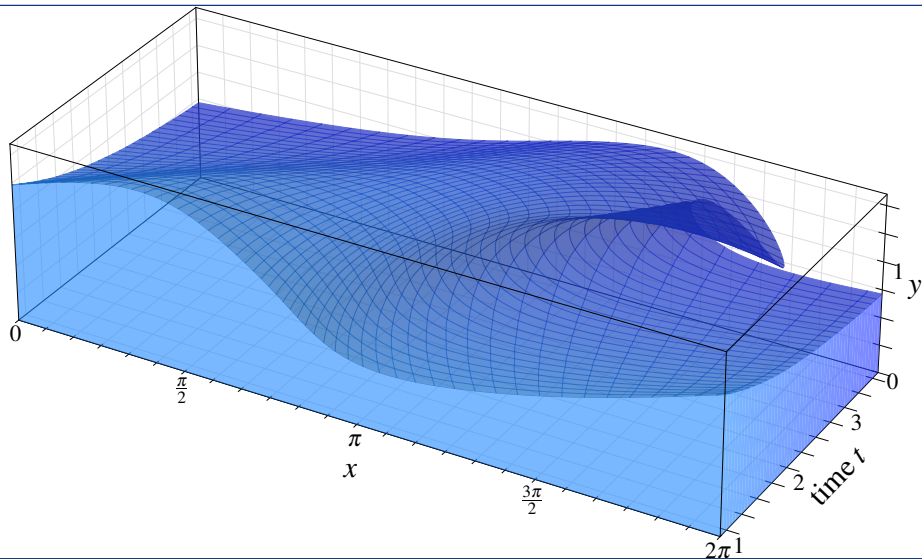
$$\begin{cases} \Delta w &= 0 & \text{in } \Omega_t \\ w &= u & \text{on } \Gamma_{s,t} \\ w &= 0 & \text{on } \Gamma_b \end{cases}$$

Hence, points on the interface $\Gamma_s(t)$ are advected in a **lagrangian** manner.

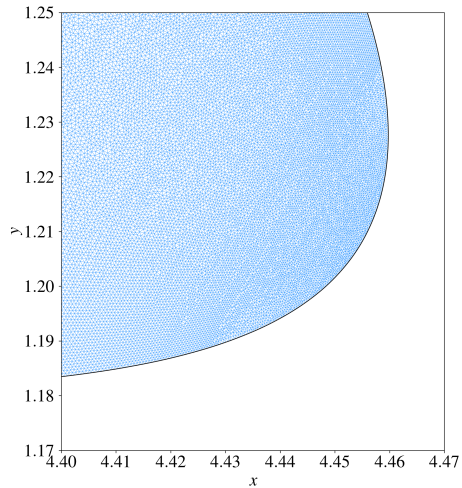
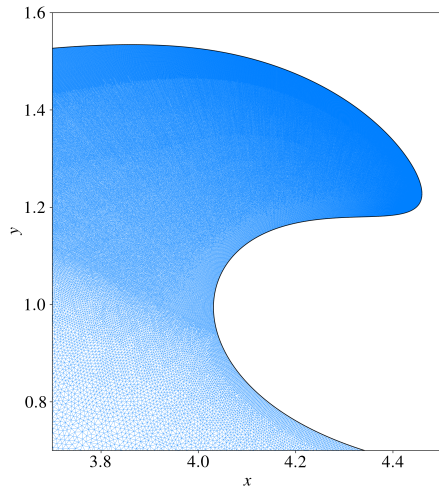
This is called the **Arbitrary Lagrangian-Eulerian** (ALE) method.



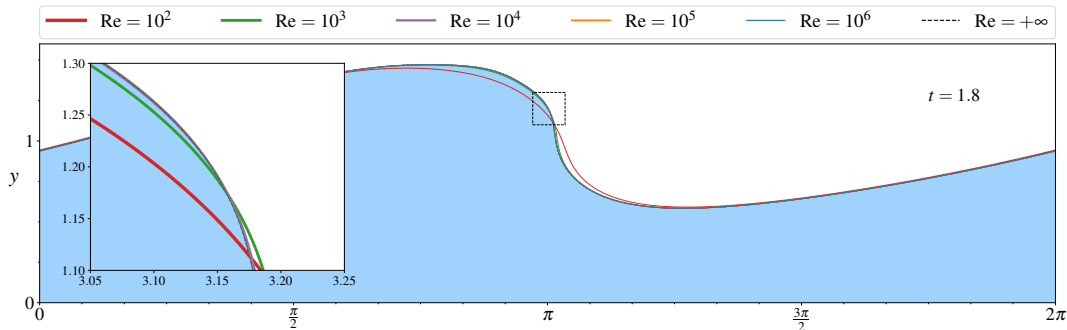
Results with $\text{Re} = 10^6$



Mesh at $Re = 10^6$



Increasing the Reynolds number Re

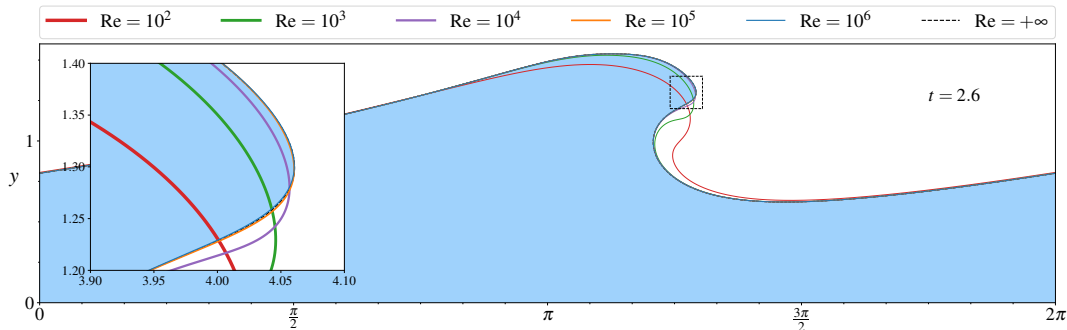


The simulation $Re = +\infty$ (i.e. the Euler solution) has been computed with the code of



[Dormy & Lacave \(2024\)](#).

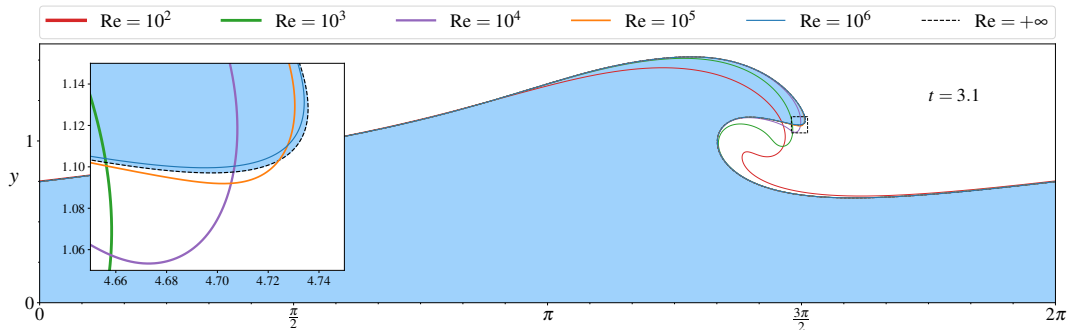
Increasing the Reynolds number Re



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Increasing the Reynolds number Re

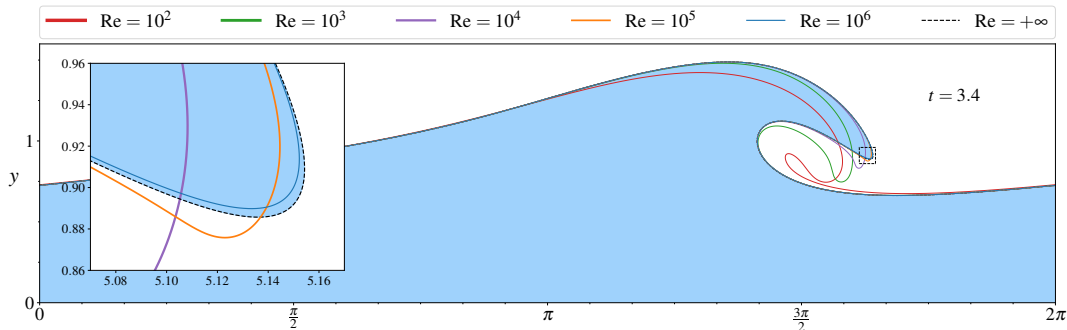


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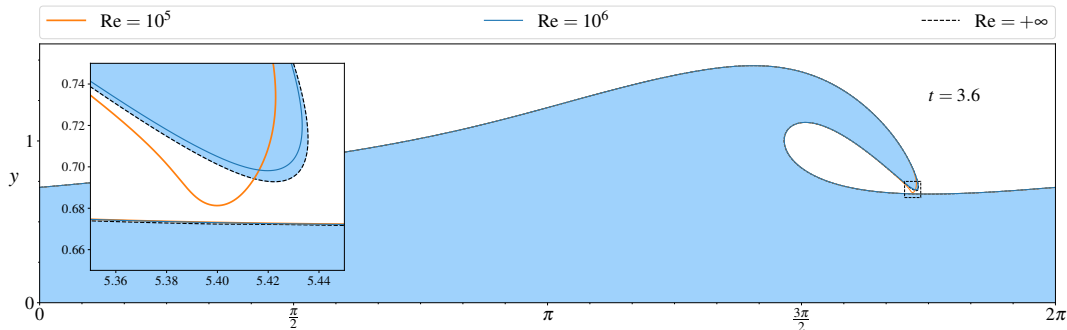
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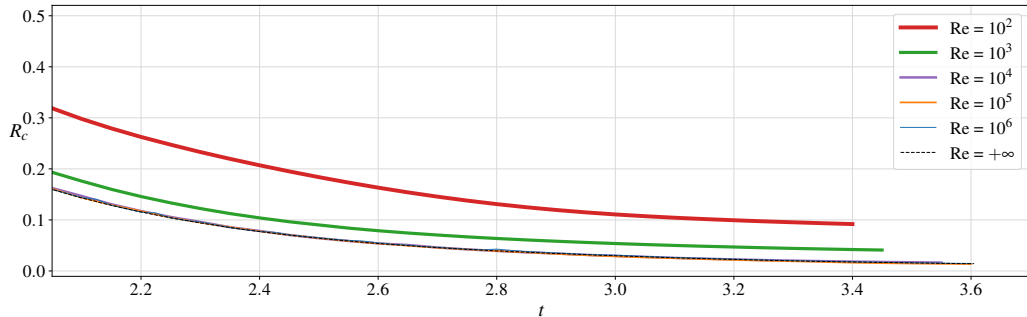
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Time evolution of the maximum curvature



where $R_C = \kappa^{-1}$ is the **curvature radius**.

Energy dissipation

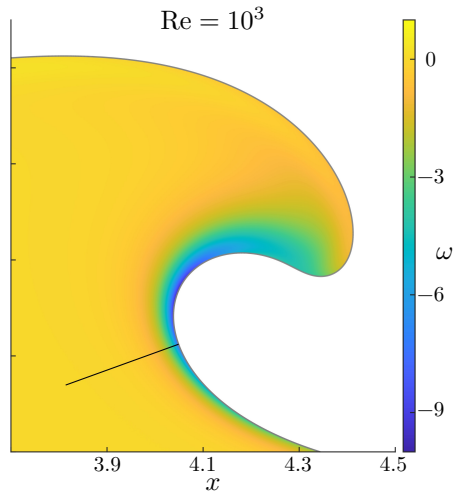
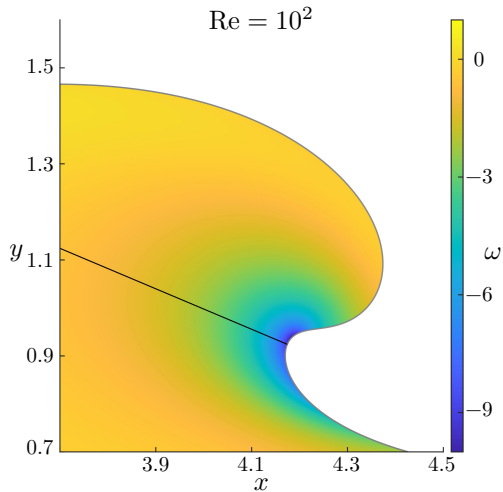
Local equation

If we multiply **Navier-Stokes** by $\mathbf{u}$, we easily get a local equation of the evolution of the **kinetic energy**

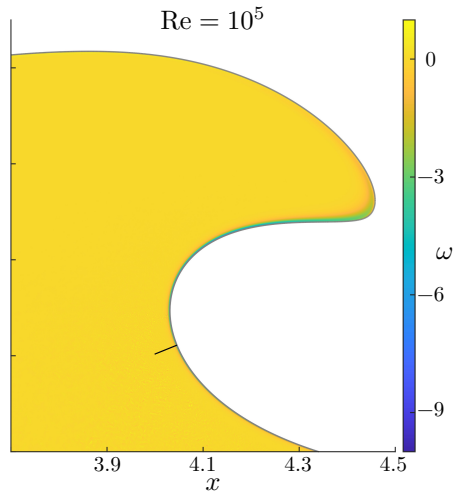
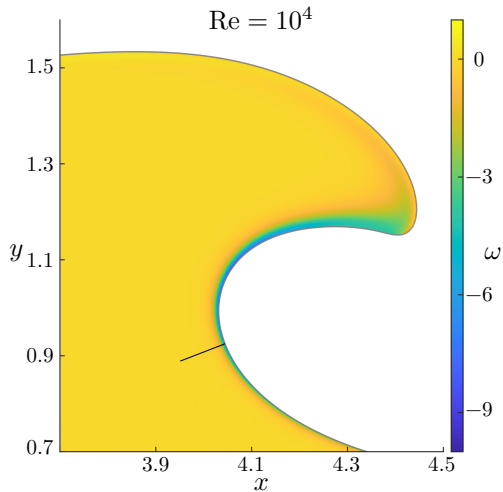
$$\partial_t \left(\frac{\mathbf{u}^2}{2} \right) = \mathbf{g} \cdot \mathbf{u} - \mathbf{u} \cdot \nabla p + \frac{1}{\text{Re}} \left[\nabla \cdot (\mathbf{u}^\perp \omega) - \omega^2 \right]$$

where $\mathbf{u}^\perp = [-u_y, u_x]$ and $\omega = \nabla^\perp \cdot \mathbf{u}$ is the **vorticity**.

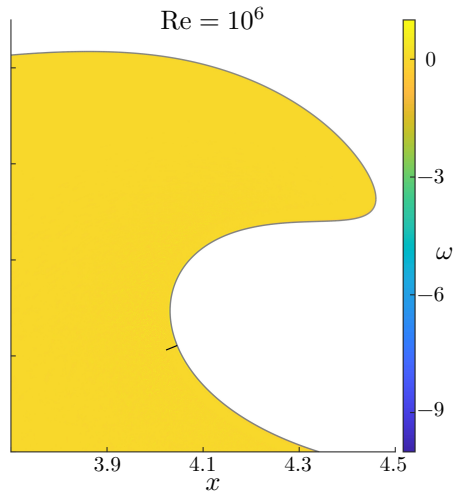
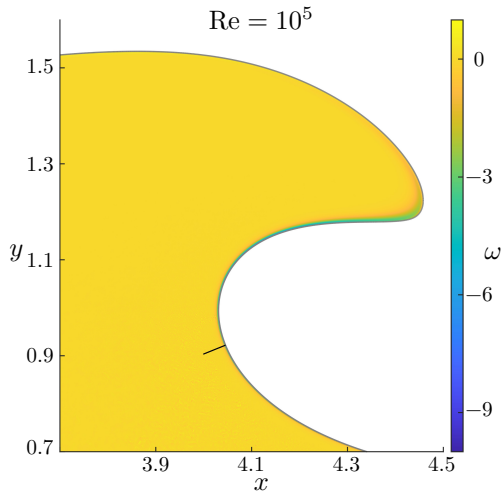
Viscous dissipation



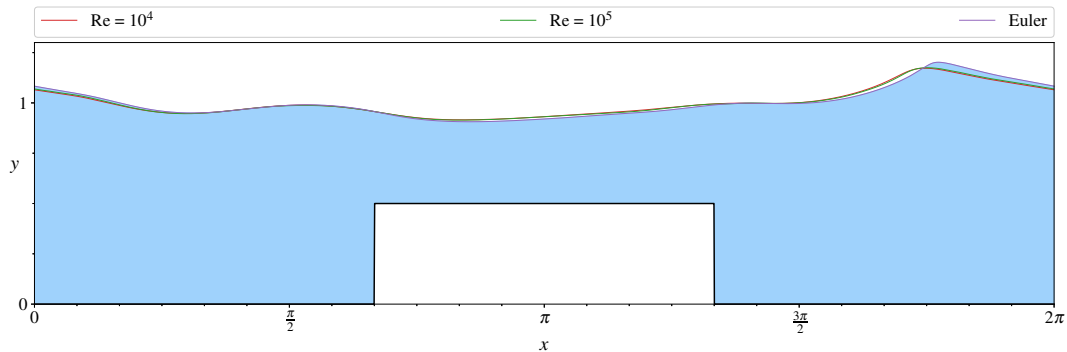
Viscous dissipation



Viscous dissipation



Non-convergence of the Navier-Stokes solution



Thank you!