Lecture 4: Differential Form on \mathbb{R}^d

Chenlin GU

DMA/ENS, PSL Research University

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Outline for section 1

- 1 k-form
 - Definition
 - Structure
- 2 Operations on k-form
 - Addition
 - Exterior Product
 - Exterior Differential
 - Pull-Back

Object

- Object: A language of multi-linear algebra to unify vector analysis.
- Something we have learned in the previous lecture:
 - Integral along regular curve: integral of 1-form

$$\int_{\gamma} F \, \mathrm{d}\gamma := \int_a^b F(t) \cdot \gamma'(t) \, \mathrm{d}t = \sum_{i=1}^d \int_a^b F_i(t) \gamma_i'(t) \, \mathrm{d}t.$$

• Green's theorem: transform an integral of 1-form to 2-form

$$\int_{D} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \int_{\partial D} P dx + Q dy.$$
 (1.1)

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Multi-linear algebra

Definition

 $\phi:(\mathbb{R}^n)^k \to \mathbb{R}$ is multi-linear form $((\mathbb{R}^n)^k)^*$ if and only if that

$$\phi(\mathbf{v}_1, \mathbf{v}_2 \cdots \alpha \mathbf{v}_i + \beta \mathbf{v}_i' \cdots \mathbf{v}_k) = \alpha \phi(\mathbf{v}_1, \mathbf{v}_2 \cdots \mathbf{v}_i \cdots \mathbf{v}_k) + \beta \phi(\mathbf{v}_1, \mathbf{v}_2 \cdots \mathbf{v}_i' \cdots \mathbf{v}_k)$$

- $\dim((\mathbb{R}^n)^*) = n$.
- Easy to prove that $dim(((\mathbb{R}^n)^k)^*) = nk$.

k-alternating-form

Definition (k-alternating-form)

 $\varphi: (\mathbb{R}^n)^k \to \mathbb{R}$ is a k-alternating-form $\Lambda^k(\mathbb{R}^n)^*$ if it is multi-linear form and once we interchange an argument, we add a factor (-1) i.e.

$$\varphi(v_1,v_2\cdots v_i,v_{i+1}\cdots v_k)=(-1)\varphi(v_1,v_2\cdots v_{i+1},v_i\cdots v_k).$$

Question: Dimension and basis of $\Lambda^k(\mathbb{R}^n)^*$.

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Theorem

We have that $\dim(\Lambda^k(\mathbb{R}^n)^*) = \binom{n}{k}$, and let $\{dx_{\alpha_1} \wedge dx_{\alpha_2} \dots \wedge dx_{\alpha_k}\}_{1 \leq \alpha_1 < \alpha_2 \dots < \alpha_k \leq n}$ be a basis such that

$$dx_{\alpha_1}\wedge dx_{\alpha_2}\cdots \wedge dx_{\alpha_k}\big(v_1,v_2,\cdots v_k\big):=\det\left(([v_i]_{\alpha_j})_{1\leqslant i,j\leqslant k}\right).$$

Proof.

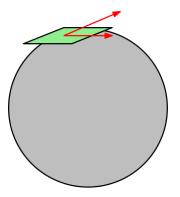
If we admit the structure of the basis, then the dimension is clear, which should be "choosing k different indexes among n". Let $\{e_i\}_{1\leq i\leq n}$ be the basis in \mathbb{R}^n , then it is easy to check that

 $\{dx_{\alpha_1} \wedge dx_{\alpha_2} \cdots \wedge dx_{\alpha_k}\}_{1 \le \alpha_1 \le \alpha_2 \cdots \le \alpha_k \le n}$ is linear independent by testing $\{e_i\}_{1 \leq i \leq n}$. Moreover, we have an explicit formula for the expression of the k – form:

$$\varphi = \sum_{1 \leqslant \alpha_1 < \alpha_2 \cdots < \alpha_k \leqslant n} \varphi(e_{\alpha_1}, e_{\alpha_2}, \cdots e_{\alpha_k}) dx_{\alpha_1} \wedge dx_{\alpha_2} \cdots \wedge dx_{\alpha_k}.$$

This proves that they are basis of $\Lambda^k(\mathbb{R}^n)^*$.

- We will make it more clear the sense of \wedge .
- For short, one can write down that $\varphi = \sum_{I} \alpha_{I} dx_{I}$, where I denote the multi-index $I = (\alpha_1, \alpha_2 \cdots \alpha_k)$.



- For a point $p \in U \subset \mathbb{R}^d$, we have $\varphi_p \in \Lambda^k(\mathbb{R}_p^n)^*$ if the vector space is the one associated to p.
- $\varphi = \sum_{I} \alpha_{I} dx_{I}$ is continuous (C¹) if for any I, α_{I} is continuous (C¹).

Example of k-form

- k = 0, just function in \mathbb{R}^n .
- $k = 1, n = 2, \Lambda^1(\mathbb{R}^2) : \varphi = \alpha dx + \beta dy.$
- $k = 2, n = 2, \Lambda^2(\mathbb{R}^2) : \varphi = \alpha dx \wedge dy$.
- $k = 1, n = 3, \Lambda^{1}(\mathbb{R}^{3}) : \varphi = \alpha dx + \beta dy + \gamma dz.$
- $k = 2, n = 3, \Lambda^2(\mathbb{R}^3) : \varphi = \alpha dx \wedge dy + \beta dy \wedge dz + \gamma dz \wedge dx$.
- $k = 3, n = 3, \Lambda^3(\mathbb{R}^3) : \varphi = \alpha dx \wedge dy \wedge dz$.

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Addition

For two k-forms, $\omega, \varphi \in \Lambda^{k}(\mathbb{R}^{n})^{*}$ that

$$\omega = \sum_{\mathrm{I}} \alpha_{\mathrm{I}} \, \mathrm{dx_{\mathrm{I}}}, \qquad \varphi = \sum_{\mathrm{I}} \beta_{\mathrm{I}} \, \mathrm{dx_{\mathrm{I}}},$$

we define that

$$\omega + \varphi := \sum_{\mathrm{I}} (\alpha_{\mathrm{I}} + \beta_{\mathrm{I}}) \, \mathrm{dx_{\mathrm{I}}}.$$

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Exterior Product (\land)

Let $\omega \in \Lambda^{k}(\mathbb{R}^{n})^{*}$ and $\varphi \in \Lambda^{s}(\mathbb{R}^{n})^{*}$ such that

$$\omega = \sum_{\mathrm{I}} \alpha_{\mathrm{I}} \, \mathrm{dx_{\mathrm{I}}}, \qquad \varphi = \sum_{\mathrm{I}} \beta \, \mathrm{dy_{\mathrm{J}}},$$

then we define the notation \wedge

$$\omega \wedge \varphi := \sum_{\mathrm{I},\mathrm{J}} \alpha_{\mathrm{I}} \beta_{\mathrm{J}} \, \mathrm{dx}_{\mathrm{I}} \wedge \mathrm{dy}_{\mathrm{J}}.$$

This gives that $\omega \wedge \varphi$ a (k + s) form.

Exterior Product (A)

Some properties:

- **2** For ω a k-form, φ , θ s-forms, then $\omega \wedge (\varphi + \theta) = \omega \wedge \varphi + \omega \wedge \theta$.
- **3** For ω a k-form, φ s-forms, then $\omega \wedge \varphi = (-1)^{\mathrm{ks}} \varphi \wedge \omega$.

Theorem

Let $\{\varphi_i\}_{1 \leq i \leq k}$ be k 1-form, then we have

$$\varphi_1 \wedge \varphi_2 \cdots \wedge \varphi_k(v_1, v_2, \cdots v_k) = \det \left((\varphi_i(v_j))_{1 \leqslant i, j \leqslant k} \right).$$

A simple corollary $dx_i \wedge dx_i = 0$.

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Exterior Differential

• For a 0-form (function), we have

$$df = \sum_{i=1}^{n} \partial_{x_i} f \, dx_i.$$

• For a k-form $\varphi = \sum_{I} \alpha_{I} dx_{I}$, then we can define $d\varphi$

$$\begin{split} \mathrm{d}\varphi &= \sum_{I} \mathrm{d}\alpha_{I} \wedge \mathrm{d}x_{I} \\ &= \sum_{I} (\sum_{i=1}^{n} \partial_{x_{i}} \alpha_{I} \, \mathrm{d}x_{i}) \wedge \mathrm{d}x_{I} \\ &= \sum_{i,I} \partial_{i} \alpha_{I} \, \mathrm{d}x_{i} \wedge \mathrm{d}x_{I}. \end{split}$$

Exterior Differential

Some properties:

Example in Green's Theorem

Green's theorem: transform an integral of 1-form to 2-form

$$\int_{D} \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \int_{\partial D} P dx + Q dy.$$
 (2.1)

- 1-form: $\varphi = Pdx + Qdy$.
- •

$$\begin{split} \mathrm{d}\varphi &= \mathrm{d} P \wedge \mathrm{d} x + \mathrm{d} Q \wedge \mathrm{d} y \\ &= \left(\frac{\partial P}{\partial x} \mathrm{d} x + \frac{\partial P}{\partial y} \mathrm{d} y\right) \wedge \mathrm{d} x + \left(\frac{\partial Q}{\partial x} \mathrm{d} x + \frac{\partial Q}{\partial y} \mathrm{d} y\right) \wedge \mathrm{d} y \\ &= \frac{\partial P}{\partial y} \mathrm{d} y \wedge \mathrm{d} x + \frac{\partial Q}{\partial x} \mathrm{d} x \wedge \mathrm{d} y \\ &= \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right) \mathrm{d} x \wedge \mathrm{d} y. \end{split}$$

• That is why we write $\int_{\partial D} \varphi = \int_{D} d\varphi$.

Interpretation of 1-form

- $\bullet \ df = \textstyle \sum_{i=1}^n \partial_{x_i} f \, dx_i.$
- We add the information of the position

$$df_p = \sum_{i=1}^n \partial_{x_i} f_p \, dx_i.$$

- $\forall v \in \mathbb{R}^n, df_p : \mathbb{R}^n \to \mathbb{R}$. Nothing but the first order differential (which is a linear map).
- Thus the two notations coincide.

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Pull-Back is the idea of df_p.

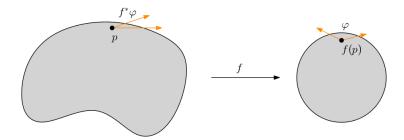
- $f: \mathbb{R}^n \to \mathbb{R}^m$ a C^1 differential map.
- $\bullet \ df_p: \mathbb{R}^n \to \mathbb{R}^m.$
- $\varphi \in \Lambda^{k}(\mathbb{R}^{m})^{*}$.
- "Pull-back" means pull the differential form \mathbb{R}^m to that of \mathbb{R}^n .
- $f^*\varphi \in \Lambda^k(\mathbb{R}^n)^*$: for $v_1 \cdots v_k \in \mathbb{R}^n$

$$\left[(f^*\varphi)_p(v_1, v_2, \cdots v_k) := \varphi_{f(p)}(df_p(v_1), df_p(v_2) \cdots df_p(v_k)) \right]. \tag{2.2}$$

Some useful properties:

- $\bullet f^*(\varphi + \omega) = f^*\varphi + f^*\omega.$
- ② For g a differentiable 0-form, $f^*(g\varphi) = f^*gf^*\varphi$.

- $(f \circ g)^* \varphi = g^*(f^* \varphi).$



Prop: For $\{\varphi_i\}_{1 \leq i \leq k}$ 1-form, $f^*(\varphi_1 \wedge \varphi_2 \cdots \wedge \varphi_k) = f^*\varphi_1 \wedge f^*\varphi_2 \cdots \wedge f^*\varphi_k$. Proof.

$$\begin{split} &f^*(\varphi_1 \wedge \varphi_2 \cdots \wedge \varphi_k)(v_1, v_2 \cdots v_k) \\ &= (\varphi_1 \wedge \varphi_2 \cdots \wedge \varphi_k)(\mathrm{d}f(v_1), \mathrm{d}f(v_2) \cdots \mathrm{d}f(v_k)) \\ &= \mathrm{det}\,(\varphi_i(\mathrm{d}f(v_j))_{1 \leqslant i,j \leqslant k}) \\ &= \mathrm{det}\,((f^*\varphi_i(v_j))_{1 \leqslant i,j \leqslant k}) \\ &= (f^*\varphi_1 \wedge f^*\varphi_2 \cdots \wedge f^*\varphi_k)(v_1, v_2 \cdots v_k). \end{split}$$



Prop: For φ a k-form and ω a s-form, $f^*(\varphi \wedge \omega) = f^*\varphi \wedge f^*\omega$.

Proof.

Let $\varphi = \sum_{I} \alpha_{I} dx_{I}$, $\omega = \sum_{J} \beta_{J} dy_{J}$.

$$f^{*}(\varphi \wedge \omega) = f^{*}\left(\sum_{I,J} \alpha_{I}\beta_{J} dx_{I} \wedge dy_{J}\right)$$

$$= \sum_{I,J} f^{*}\alpha_{I}f^{*}\beta_{J} df_{I} \wedge df_{J}$$

$$= \left(\sum_{I} f^{*}\alpha_{I} df_{I}\right) \wedge \left(\sum_{J} f^{*}\beta_{J} df_{J}\right)$$

$$= f^{*}\varphi \wedge f^{*}\omega.$$